

Algorithm Design

- Consider the following general constrained nonconvex optimization problem:

$$\min_{\mathbf{v}} F(\mathbf{v}), \quad \text{subject to } \mathbf{v} \in \mathcal{C}$$

- SGD performs the following update at the t -th step ($t \geq 1$):

$$\mathbf{v}_t = \Pi_{\mathcal{C}} \left[\mathbf{v}_{t-1} - \eta \tilde{\nabla} F(\mathbf{v}_{t-1}; \zeta_t) \right]$$

where $\Pi_{\mathcal{C}}[\cdot]$ denotes projection operator onto \mathcal{C} , and $\tilde{\nabla} F(\mathbf{v}_{t-1}; \zeta_t)$ denotes unbiased gradient estimator of $\nabla F(\mathbf{v}_{t-1})$

- What if there is no access to $\tilde{\nabla} F(\mathbf{v}_{t-1}; \zeta_t)$, but instead stochastic vector $\Gamma(\mathbf{v}; \zeta)$ as unbiased estimate of *scaled* gradient:

$$\mathbb{E}_{\zeta} [\Gamma(\mathbf{v}; \zeta)] = D(\mathbf{v}) \nabla F(\mathbf{v})$$

- Generalized eigenvector computation (GEV) (Principal component analysis (PCA), Partial least squares regression, Fisher's linear discriminant analysis (LDA), canonical correlation analysis (CCA), etc.)

Stochastic Scaled-Gradient Descent

- SSGD performs the update:

$$\mathbf{v}_t = \Pi_{\mathcal{C}} [\mathbf{v}_{t-1} - \eta \Gamma(\mathbf{v}_{t-1}; \zeta_t)] \quad \text{where } \mathbb{E}_{\zeta} [\Gamma(\mathbf{v}; \zeta)] = D(\mathbf{v}) \nabla F(\mathbf{v})$$

- Example:** Generalized Rayleigh quotient given a unit spherical constraint:

$$\min_{\mathbf{v}} -\frac{\mathbf{v}^{\top} \mathbf{A} \mathbf{v}}{\mathbf{v}^{\top} \mathbf{B} \mathbf{v}} \quad \text{subject to } \mathbf{v} \in \mathcal{S}^{d-1} = \{\mathbf{v} \in \mathbb{R}^d : \|\mathbf{v}\| = 1\}$$

- The first-order derivative with respect to \mathbf{v}

$$\nabla_{\mathbf{v}} \left[-\frac{\mathbf{v}^{\top} \mathbf{A} \mathbf{v}}{\mathbf{v}^{\top} \mathbf{B} \mathbf{v}} \right] = -\frac{(\mathbf{v}^{\top} \mathbf{B} \mathbf{v}) \mathbf{A} \mathbf{v} - (\mathbf{v}^{\top} \mathbf{A} \mathbf{v}) \mathbf{B} \mathbf{v}}{(1/2)(\mathbf{v}^{\top} \mathbf{B} \mathbf{v})^2}$$

- Replacing the denominator, denoted as $D(\mathbf{v})$, by the constant 1:

$$\mathbf{v}_t = \Pi_{\mathcal{S}^{d-1}} \left[\mathbf{v}_{t-1} + \eta ((\mathbf{v}_{t-1}^{\top} \tilde{\mathbf{B}}' \mathbf{v}_{t-1}) \tilde{\mathbf{A}} \mathbf{v}_{t-1} - (\mathbf{v}_{t-1}^{\top} \tilde{\mathbf{A}} \mathbf{v}_{t-1}) \tilde{\mathbf{B}}' \mathbf{v}_{t-1}) \right]$$

where the bracketed term is unbiased estimate of $-\Gamma(\mathbf{v}; \zeta)$

Previous Works

- Oja's online PCA iteration [Oja82] (Special case where $\tilde{\mathbf{B}}$ is taken as \mathbf{I})
- Procedures for efficient online canonical eigenvectors estimation has been explored [AMMS17, GGS⁺19, CLY⁺19].
- [BPF⁺18] studied the CCA problem and proposed a two-time-scale online iteration ("Gen-Oja"), obtained $1/\sqrt{N}$.

Our Contributions

- We propose the (**SSGD**) **algorithm**—which generalizes the classical SGD algorithm and has a wider range of applications.
- We provide a local convergence analysis for convex spherical-constraint objective functions. Starting with a warm initialization, matches a known **information-theoretic lower bound**[MBM18].
- By applying SSGD to the GEV problem, we give a positive answer to the question raised by [ACLS12] regarding to the existence of an efficient online GEV algorithm. Specifically, in the case of CCA, our SSGD algorithm uses as few as two samples at each update, **does not incur intermediate and expensive computational cost** while achieving a **polynomial convergence rate guarantee**

Theoretical Results: Assumptions

Initialization:

$$\|\mathbf{v}_0 - \mathbf{v}^*\| \leq \min \left\{ \frac{D\mu}{2^5 \rho}, \delta \right\} \quad (1)$$

Assumption (Smoothness Assumption): For any $\mathbf{v} \in \{\mathbf{v} : \|\mathbf{v}\| \leq 1, \|\mathbf{v} - \mathbf{v}^*\| \leq \delta\}$, we assume that $D(\mathbf{v})$ is L_D -Lipschitz, $F(\mathbf{v})$ is L_F -Lipschitz, $\nabla F(\mathbf{v})$ is L_K -Lipschitz and $\nabla^2 F(\mathbf{v})$ is L_Q -Lipschitz, where L_D, L_F, L_K, L_Q are fixed positive constants.

Assumption (Sub-Weibull Tail): For some fixed $\mathcal{V} \in (0, \infty)$ and for all $\mathbf{v} \in \mathcal{C}$, we assume that the stochastic vectors $\Gamma(\mathbf{v}; \zeta)$ satisfy

$$\mathbb{E} \exp \left(\left\| \frac{\Gamma(\mathbf{v}; \zeta)}{\mathcal{V}} \right\|^\alpha \right) \leq 2 \quad (2)$$

Finite-Sample Convergence Rate

Corollary (Finite-Sample): Assume Assumptions 1 and 2 and the initialization condition (1). For fixed positive constants ϵ and sample size T , set the step size as $\eta(T) = \Theta \left(\frac{\log T}{D\mu T} \right)$, satisfying some scaling condition, there exists an event \mathcal{H} with

$$\mathbb{P}(\mathcal{H}) \geq 1 - \left(14 + 8 \left(\frac{3}{\alpha} \right)^{\frac{2}{\alpha}} \log^{-\frac{\alpha+2}{\alpha}} \epsilon^{-1} \right) T \epsilon,$$

such that on the event \mathcal{H} the iterates generated by the SSGD algorithm satisfy

$$\|\mathbf{v}_T - \mathbf{v}^*\| \lesssim \frac{G_\alpha \mathcal{V}}{D\mu} \log^{\frac{\alpha+2}{2\alpha}} \epsilon^{-1} \sqrt{\frac{\log T}{T}}.$$

- In the case of CCA, the ($\alpha = 1/2$) sub-Weibull parameter \mathcal{V} in that case scales with \sqrt{d} and thus the local rate is the minimax-optimal rate $O(\sqrt{d/T})$ up to a polylogarithmic factor.

Asymptotic Normality via Trajectory Averaging

Assumption (Mean-Squared Smoothness): There exists a positive constant L_S such that for all $\mathbf{v}, \mathbf{v}' \in \{\mathbf{v} : \|\mathbf{v}\| \leq 1, \|\mathbf{v} - \mathbf{v}^*\| \leq \delta\}$ and $t \geq 1$, we have for ζ

$$\mathbb{E} \|\Gamma(\mathbf{v}; \zeta) - \Gamma(\mathbf{v}'; \zeta)\|^2 \leq L_S^2 \|\mathbf{v} - \mathbf{v}'\|^2$$

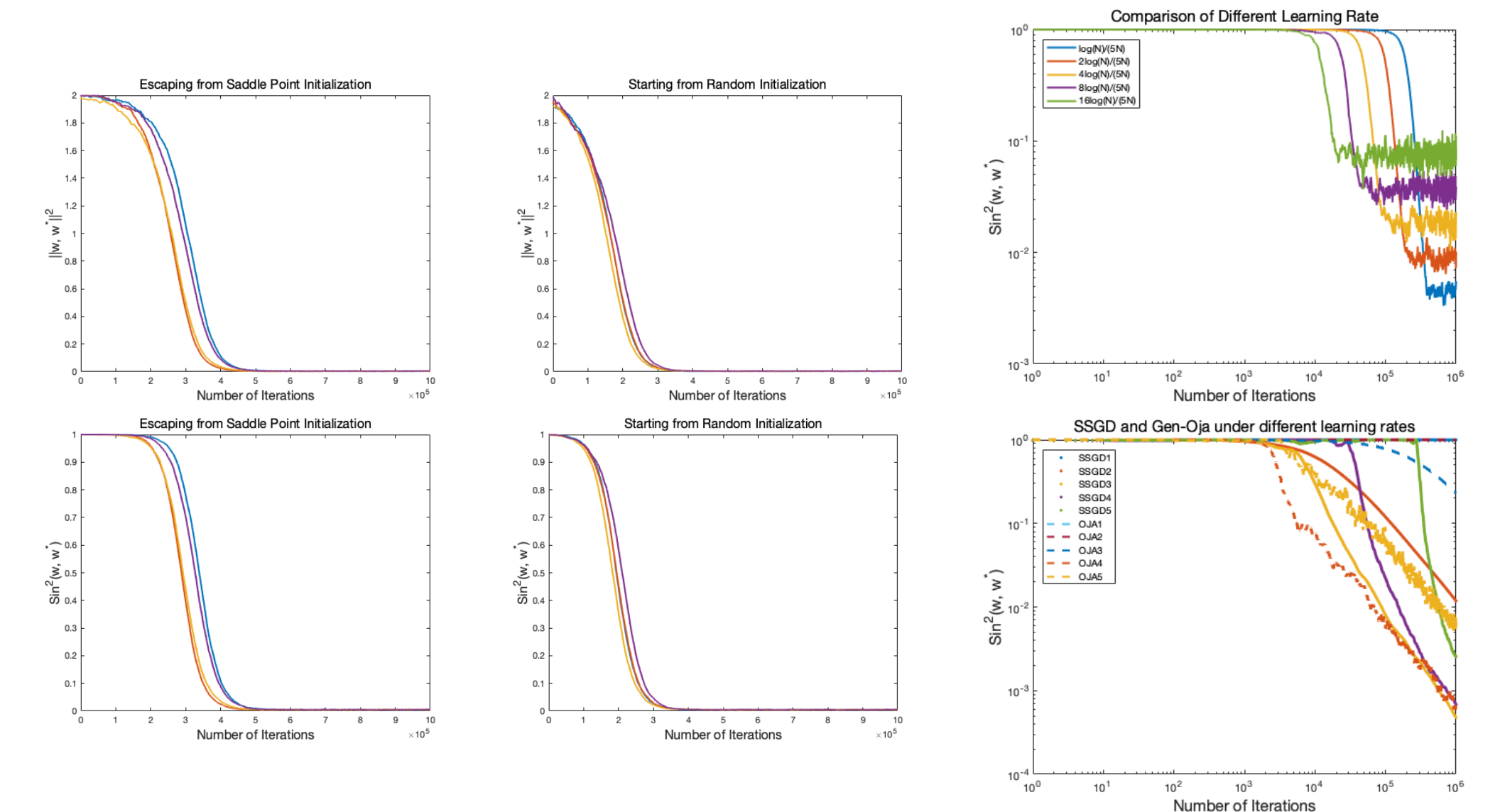
Theorem (Asymptotic Normality): Assume Assumptions 1, 2, 3 and initialization condition (1). If we choose the step size η such that $\eta \rightarrow 0$ as the total sample size $T \rightarrow \infty$, where

$$T \eta^2 \log^{\frac{2\alpha+4}{\alpha}} T \rightarrow 0, \quad T \eta \log^{-\frac{\alpha+2}{\alpha}} T \rightarrow \infty \quad \text{a.s.}$$

we obtain Gaussian convergence in distribution:

$$\sqrt{T} \left(\bar{\mathbf{v}}_T^{(\eta)} - \mathbf{v}^* \right) \xrightarrow{d} \mathcal{N}(\mathbf{0}, D^{-2} \cdot \mathcal{M}_*^{-1} \Sigma_* \mathcal{M}_*)$$

Experiments



- Potential future works:** Sharper rate of escape of saddle points for SSGD, study global convergence for generic Riemannian manifolds, etc.

Reference

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