
Taming the Noise in Reinforcement Learning via Soft Updates

— Supplementary Material —

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CONVERGENCE OF G-LEARNING

In this section we prove the convergence of G to the optimal G^* , with probability 1, under the G-learning update rule

$$G(s_t, a_t) \leftarrow (1 - \alpha_t)G(s_t, a_t) + \alpha_t \left(c_t - \frac{\gamma}{\beta} \log \left(\sum_{a'} \rho(a'|s_{t+1}) e^{-\beta G(s_{t+1}, a')} \right) \right). \quad (1)$$

Recall that the supremum norm is defined as $\|x\|_\infty = \max_i |x_i|$, and that the optimal G function satisfies

$$G^*(s, a) = \mathbb{E}_\theta[c|s, a] - \frac{\gamma}{\beta} \mathbb{E}_p \left[\log \sum_{a'} \rho(a'|s') e^{-\beta G^*(s', a')} \right] \equiv \mathbf{B}^*[G^*]_{(s,a)}. \quad (2)$$

The convergence proof relies on the following Lemma.

Lemma 1. *The operator $\mathbf{B}^*[G]_{(s,a)}$ defined in (3) is a contraction in the supremum norm.*

Proof. Let us define

$$\mathbf{B}^\pi[G]_{(s,a)} = k^\pi(s, a) + \gamma \sum_{s', a'} p(s'|s, a) \pi(a'|s') G(s', a'), \quad (4)$$

where

$$k^\pi(s, a) = \mathbb{E}_\theta[c|s, a] + \frac{\gamma}{\beta} \sum_{s', a'} p(s'|s, a) \pi(a'|s') \log \frac{\pi(a'|s')}{\rho(a'|s')}. \quad (5)$$

Now, for any policy π , the operator (4) is a contraction under the supremum norm [1], i.e. for any G_1 and G_2

$$\|\mathbf{B}^\pi[G_1] - \mathbf{B}^\pi[G_2]\|_\infty \leq \gamma \|G_1 - G_2\|_\infty. \quad (6)$$

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Also note that

$$\mathbf{B}^*[G_i]_{(s,a)} = \min_\pi \mathbf{B}^\pi[G_i]_{(s,a)}, \quad (7)$$

and that the optimum is achieved for

$$\pi_{G_i}(a|s) = \frac{\rho(a|s) e^{-\beta G_i(s,a)}}{\sum_{a'} \rho(a'|s) e^{-\beta G_i(s,a')}}. \quad (8)$$

The Lemma now follows from

$$\begin{aligned} & \|\mathbf{B}^*[G_1] - \mathbf{B}^*[G_2]\|_\infty \\ &= \max_{(s,a)} |\mathbf{B}^*[G_1]_{(s,a)} - \mathbf{B}^*[G_2]_{(s,a)}| \\ &= \max_{(s,a)} |\mathbf{B}^{\pi_{G_1}}[G_1]_{(s,a)} - \mathbf{B}^{\pi_{G_2}}[G_2]_{(s,a)}| \end{aligned} \quad (9)$$

(choose $i = \arg \min \mathbf{B}^{\pi_{G_i}}[G_i]_{(s,a)}$)

$$\begin{aligned} & \leq \max_{(s,a)} \max_{i=1,2} |\mathbf{B}^{\pi_{G_i}}[G_1]_{(s,a)} - \mathbf{B}^{\pi_{G_i}}[G_2]_{(s,a)}| \\ &= \max_{i=1,2} \|\mathbf{B}^{\pi_{G_i}}[G_1] - \mathbf{B}^{\pi_{G_i}}[G_2]\|_\infty \\ & \leq \gamma \|G_1 - G_2\|_\infty. \quad \square \end{aligned}$$

The update equation (1) of the algorithm can be written as a stochastic iteration equation

$$G_{t+1}(s_t, a_t) = (1 - \alpha_t)G_t(s_t, a_t) + \alpha_t (\mathbf{B}^*[G_t]_{(s_t, a_t)} + z_t(c_t, s_{t+1})) \quad (10)$$

where the random variable z_t is

$$z_t(c_t, s_{t+1}) \equiv -\mathbf{B}^*[G_t]_{(s_t, a_t)} + c_t - \frac{\gamma}{\beta} \log \sum_{a'} \rho(a'|s_{t+1}) e^{-\beta G_t(s_{t+1}, a')}. \quad (11)$$

Note that z_t has expectation 0. Many results exist for iterative equations of the type (10). In particular, given conditions

$$\sum_t \alpha_t = \infty; \quad \sum_t \alpha_t^2 < \infty, \quad (12)$$

the contractive nature of \mathbf{B}^* , infinite visits to each pair (s_t, a_t) and assuming that $|z_t| < \infty$, G_t is guaranteed to converge to the optimal G^* with probability 1 [1, 2].

References

- [1] Dimitri P Bertsekas. *Dynamic programming and optimal control*, volume 1,2. Athena Scientific Belmont, MA, 1995.
- [2] Vivek S Borkar. Stochastic approximation. *Cambridge Books*, 2008.